

LaTeX abstract template
for the International Scientific Conference
“RCD: Nonlinear Dynamics, Mechanics and Robotics”

First Author¹, Second Author¹, and Third Author²

¹ *First and Second Author’s Affiliation, City, Country*

² *Third Author’s Affiliation, City, Country*

This is a $\text{\LaTeX}$ abstract template for the International Scientific Conference “RCD: Nonlinear Dynamics, Mechanics and Robotics”.

- The conference will be held from November 23 to 27, 2026, at Udmurt State University in Izhevsk, Russia.
- The preferred language for theses is English.
- The total length of the abstract should be **one or two pages**.
- All accepted abstracts will be included in the abstract book, which will be distributed to participants of the conference.

For reference citations, please use the examples below for books [1] and articles [2].

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References

- [1] Borisov A. V., Mamaev I. S., *Rigid Body Dynamics*, De Gruyter Stud. Math. Phys., vol. 52, Berlin: De Gruyter, 2018.
- [2] Kozlov V. V., Solvable Algebras and Integrable Systems, *Regul. Chaotic Dyn.*, 2024, vol. 29, no. 5, pp. 717–727.